

# **Root Estimation using Newton-Raphson**

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## 1. Univariate Case

Consider the Taylor Series of a function,  $f$ , of one variable,  $x$ :

$$f(x + dx) = f(x) + \frac{\partial f}{\partial x} \cdot dx + \frac{1}{2} \cdot \frac{\partial^2 f}{\partial x^2} \cdot (dx)^2 + \dots$$

As an approximation:

$$f(x + dx) \approx f(x) + \frac{\partial f}{\partial x} \cdot dx$$

We can use this relation to find the value of  $dx$  such that  $f(x + dx) \approx 0$  ie. the value  $x + dx$  will be close to the 'root' of  $f$ .

If  $f(x + dx) \approx 0$  then:

$$0 \approx f(x) + \frac{\partial f}{\partial x} \cdot dx$$

$$\therefore -f(x) \approx \frac{\partial f}{\partial x} \cdot dx$$

$$\therefore -\frac{f(x)}{\frac{\partial f}{\partial x}} \approx dx$$

$$\therefore dx \approx -\frac{f(x)}{\frac{\partial f}{\partial x}}$$

So, we can use this value of  $dx$  to find  $x + dx$ , ie:

$$x + dx \approx x - \frac{f(x)}{\frac{\partial f}{\partial x}}$$

This new value of  $x$  ( $x_{new}$ ):

$$x_{new} = x + dx \approx x - \frac{f(x)}{\frac{\partial f}{\partial x}}$$

gives rise to a new value of  $f$  ( $f_{new}$ ):

$$f_{new} = f(x_{new}) = f(x + dx) \approx f\left(x - \frac{f(x)}{\frac{\partial f}{\partial x}}\right)$$

which will be closer to 0 than  $f(x)$  was. Of course if the value of  $f_{new}$  is not as close to 0 as we would like, we can just set the value of  $x$  to be  $x_{new}$  and perform the process again, ie.:

$$x_{new} = x_{old} - \frac{f(x_{old})}{f'(x_{old})}$$

$$\text{where } f'(x_{old}) = \left. \frac{\partial f}{\partial x} \right|_{x=x_{old}}$$

We can keep on iterating like this until our value for  $f_{new}$  is "close enough" to 0, ie. within our desired tolerance. This is the essence of the Newton-Raphson algorithm for finding the root of a function.

In applying Newton-Raphson there is one practical problem: determining  $f'(x)$ . Quite often the functional form of  $f$  is not known, eg.  $f(x)$  could simply be the value in a cell of a complex spreadsheet. Not knowing the equation for  $f(x)$  means not being able to determine  $f'(x)$ . In such a situation, however,  $f'(x)$  can be approximated using the difference operator:

$$f'(x) \approx \frac{f(x + dx) - f(x)}{dx}$$

The smaller  $dx$  is, the closer the difference operator will come to the true value for  $f'(x)$ .

The Newton-Raphson algorithm, therefore, can be stated as:

1. Start with an initial value for  $x$ , being a guess as to what the root of the function is;
2. Set  $x_{old} = x$ ;
3. Calculate  $f_{old} = f(x_{old})$ ;
4. Compare  $f_{old}$  with 0 to see how far away from 0 we are;
5. If  $f_{old}$  is close enough to 0 then stop – we have found that  $x_{old}$  is close enough to the real root of  $f$ .
6. If  $f_{old}$  is not close enough to 0 then calculate  $f'(x)$ . This requires two separate calculations: one to calculate  $f(x + h)$  and the other to calculate  $f'(x)$ ;
7. Calculate  $x_{new}$  from the values of  $f'(x)$ ,  $f_{old}$  and  $x_{old}$  we have just determined above, using the formula specified above;
8. Set  $x_{old} = x_{new}$ ;
9. Go to step 3 with this new value of  $x_{old}$ .

## 2. Multivariate Case

The above univariate case can be extended to the multivariate case quite simply. Consider the two variable case:  $f(x_1, x_2)$ . Again, we start with the Taylor Series expansion of  $f$ , but this time with two variables,  $x_1$  and  $x_2$ :

$$f(x_1 + dx_1, x_2 + dx_2) = f(x_1, x_2) + \frac{\partial f}{\partial x_1} \cdot dx_1 + \frac{\partial f}{\partial x_2} \cdot dx_2 + \dots$$

Again, as an approximation:

$$f(x_1 + dx_1, x_2 + dx_2) \approx f(x_1, x_2) + \frac{\partial f}{\partial x_1} \cdot dx_1 + \frac{\partial f}{\partial x_2} \cdot dx_2$$

If  $f(x_1 + dx_1, x_2 + dx_2) \approx 0$  then:

$$0 \approx f(x_1, x_2) + \frac{\partial f}{\partial x_1} \cdot dx_1 + \frac{\partial f}{\partial x_2} \cdot dx_2$$

$$\therefore -f(x_1, x_2) \approx \frac{\partial f}{\partial x_1} \cdot dx_1 + \frac{\partial f}{\partial x_2} \cdot dx_2$$

In matrix notation:

$$\therefore -f(x_1, x_2) \approx \begin{bmatrix} \frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} \end{bmatrix} \cdot \begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix}$$

The problem here, of course, is that we have one equation but two unknowns resulting in an infinite number of solutions. Therefore, in order to have a unique solution we require two equations, ie. two different functions which both depend on  $x_1$  and  $x_2$ . If this is the case then we have the equations:

$$-f_1(x_1, x_2) \approx \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \end{bmatrix} \cdot \begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix}$$

$$-f_2(x_1, x_2) \approx \begin{bmatrix} \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix} \cdot \begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix}$$

which simplifies to:

$$-\begin{bmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{bmatrix} \approx \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix} \cdot \begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix}$$

or

$$-\mathbf{f} \approx \mathbf{J} \cdot \mathbf{dx}$$

where  $\mathbf{f}$  is the vector of  $f_i(\mathbf{x})$ ,  $\mathbf{J}$  is the Jacobian matrix and  $\mathbf{dx}$  is the vector of  $dx_i$ s. Rearranging for  $\mathbf{dx}$  gives:

$$\mathbf{dx} \approx -\mathbf{J}^{-1}\mathbf{f}$$

and the resulting vector from

$$\mathbf{x} - \mathbf{J}^{-1}\mathbf{f}$$

provides our estimates of  $x_i + dx_i$  which we can use to generate  $\mathbf{f}_{new}$  which can then be tested to see if each  $f_i$  is close enough to the target value to make  $\mathbf{x} - \mathbf{J}^{-1}\mathbf{f}$  our estimate of the root of  $\mathbf{f}$ .

The problem with multivariate Newton-Raphson is that the more variates there are, the more calculations need to be done. When we had one variate, we needed to calculate the estimate of  $f'(x)$  which involved 2

calculations:  $f(x + dx)$  and  $f'(x)$ . With the bivariate case presented above we now have to calculate 4 partial derivatives, with each partial derivative requiring 2 calculations, ie. a total of 8 calculations to get  $\mathbf{J}$ . A trivariate case has 9 partial derivatives in its Jacobian matrix, ie. 18 calculations for  $\mathbf{J}$ . Generalizing we see that for the n-variate case, the calculation of  $\mathbf{J}$  requires  $2n^2$  separate calculations to be done. And this is before we even start to invert  $\mathbf{J}$ . Consequently, while Newton-Raphson lends itself well to the multivariate case, in its application we must be mindful of the computational effort required.